



## **Engineering Center Steyr GmbH & Co KG (ECS)**

**Dynamic Simulation in Vehicle Engineering 10.-11. Mai 2012**  
**Generating Verified Load Data Using Virtual Iteration Method**

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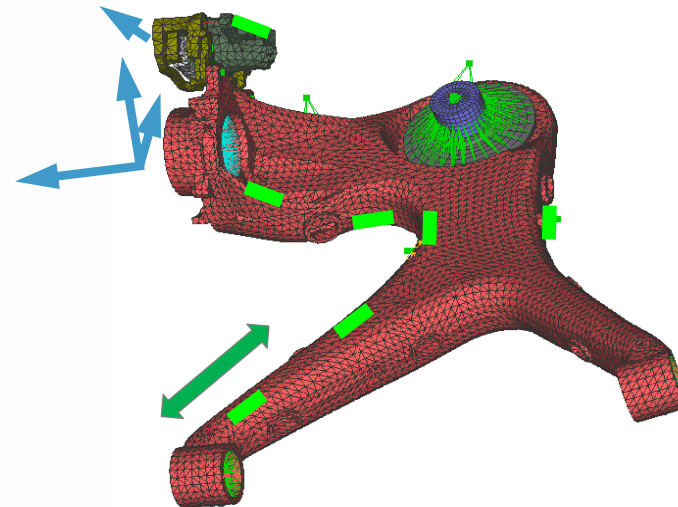
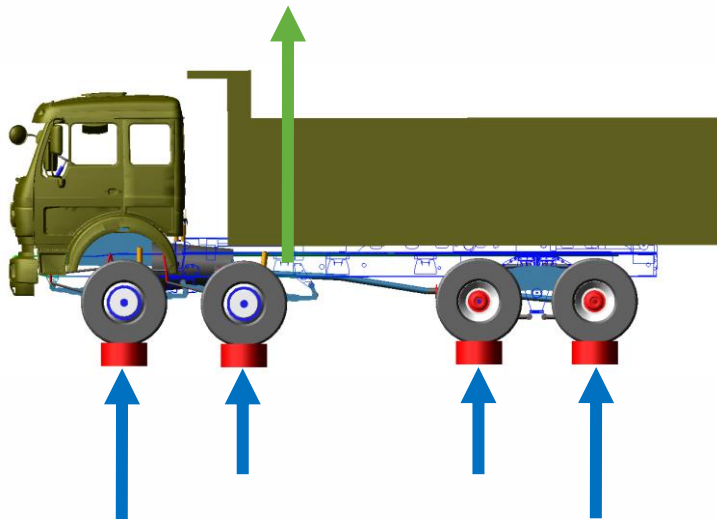
## Content

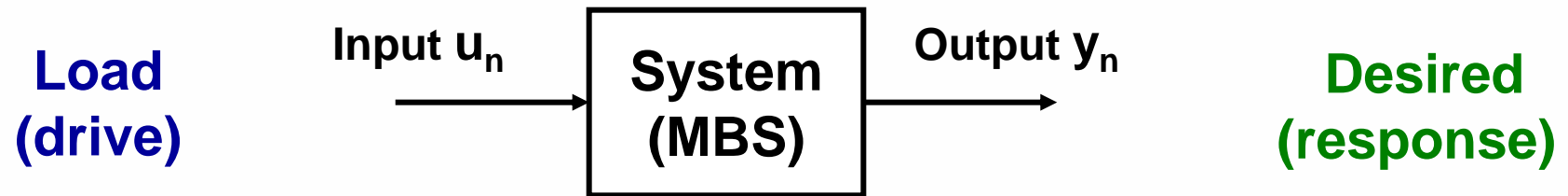
- **Motivation for Virtual Iteration**
- **General Approach of Virtual Iteration**
- **Example „8x4 Truck” (Full Vehicle) with invariant road excitation for fatigue and comfort**
- **Example „Suspension Test Rig” with invariant strains for test bench modifications**



## Motivation:

- to generate **external loads** based on internal, measured **response**
- to get invariant excitations for parameter variation
- for fatigue and comfort investigation
- for modification/optimization of test bench concepts





- Inverse non-linear problem: *find loads for given responses*

**Drive**

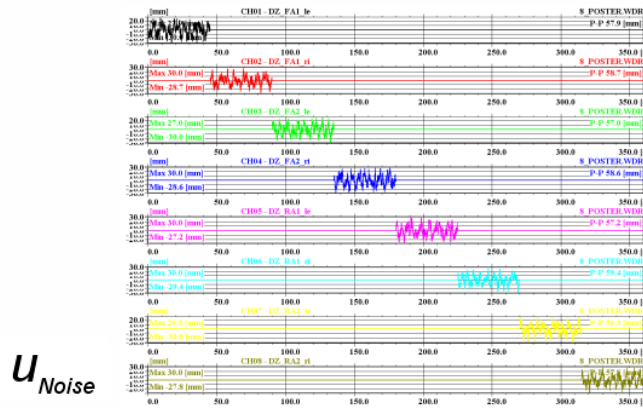
- Forces (external)
- Displacements (absolute)

**Response**

- Accelerations
- Strains
- Displacements (relative)
- Forces (internal)

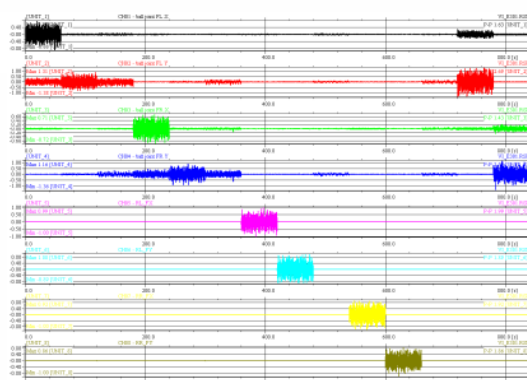
# Virtual Iteration General Approach

## 1. Pink noise

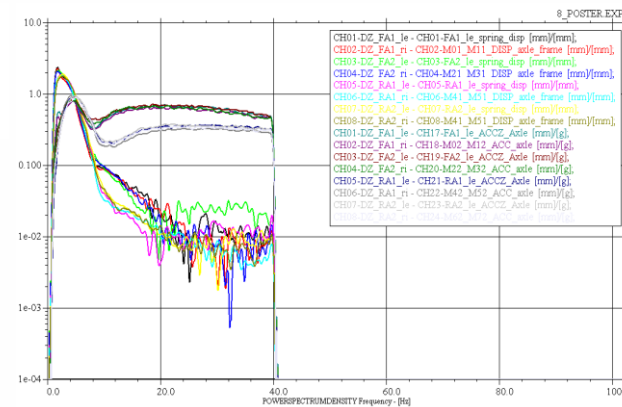
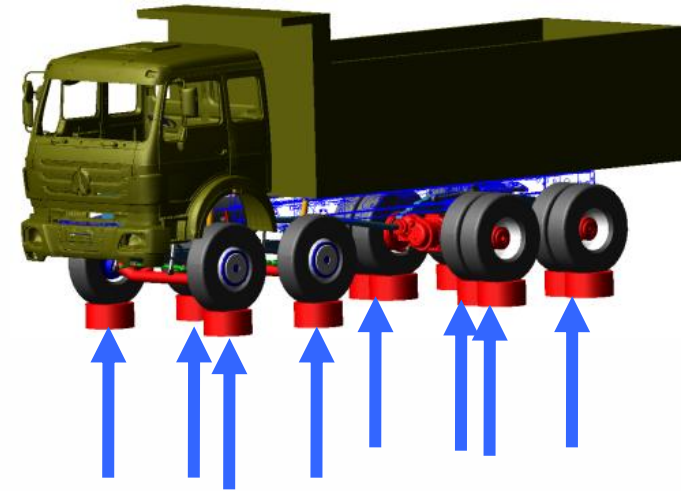


$U_{Noise}$

$y_{Noise}$



$$F = \frac{y_{Noise}}{U_{Noise}}$$



$$U_0 = F^{-1} y_{Desired}$$

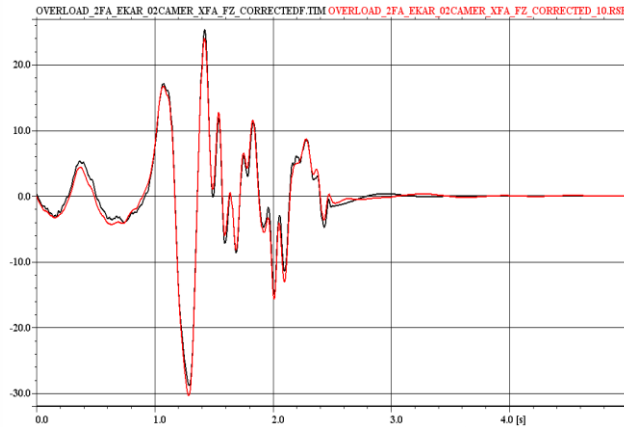


## 2. Response of noise

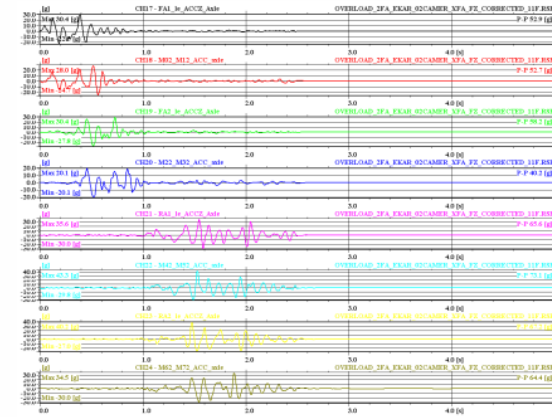
## 3. Transfer function

# Virtual Iteration General Approach

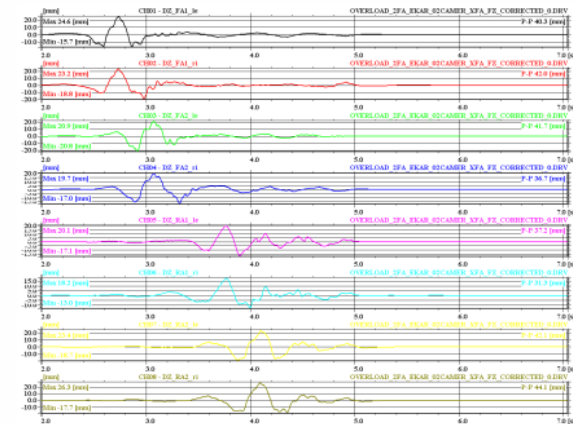
## 6. Response = desired



## 5. Response



## 4. Drive signal



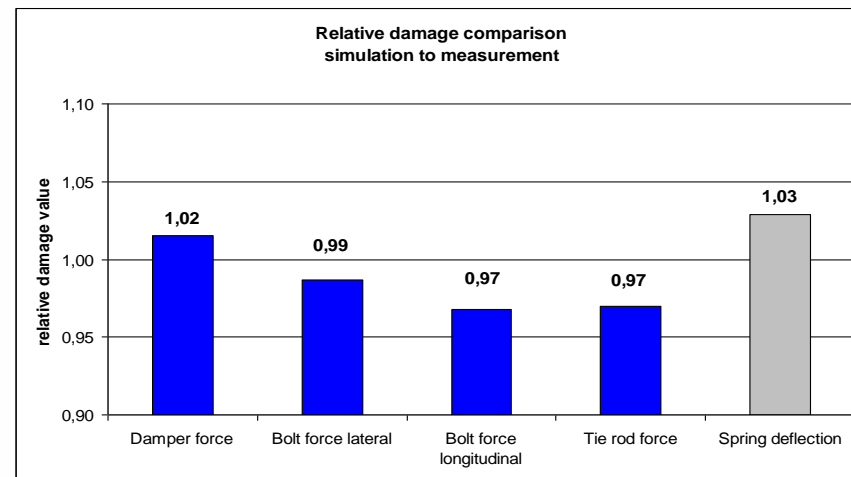
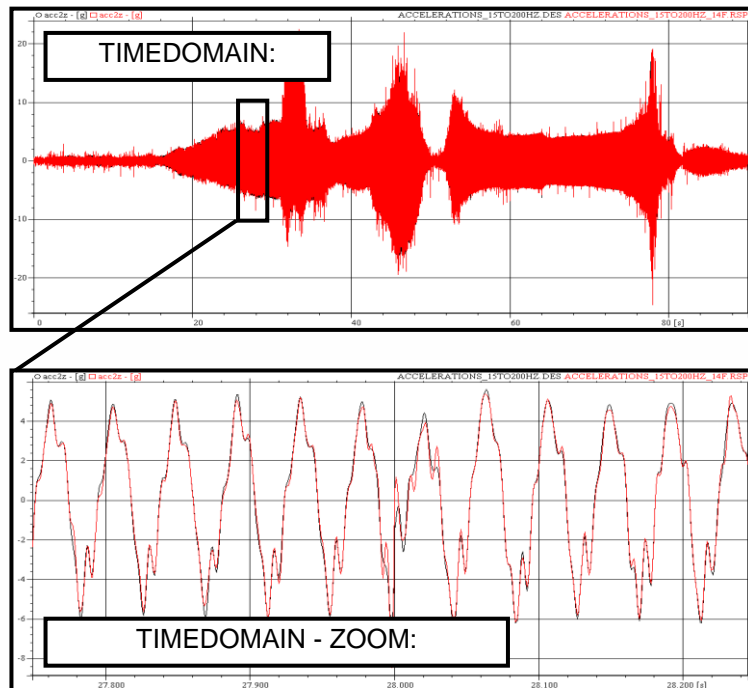
$$u_{n+1} = u_n + F^{-1} (y_{Desired} - y_n)$$

$$u_0 = F^{-1} y_{Desired}$$

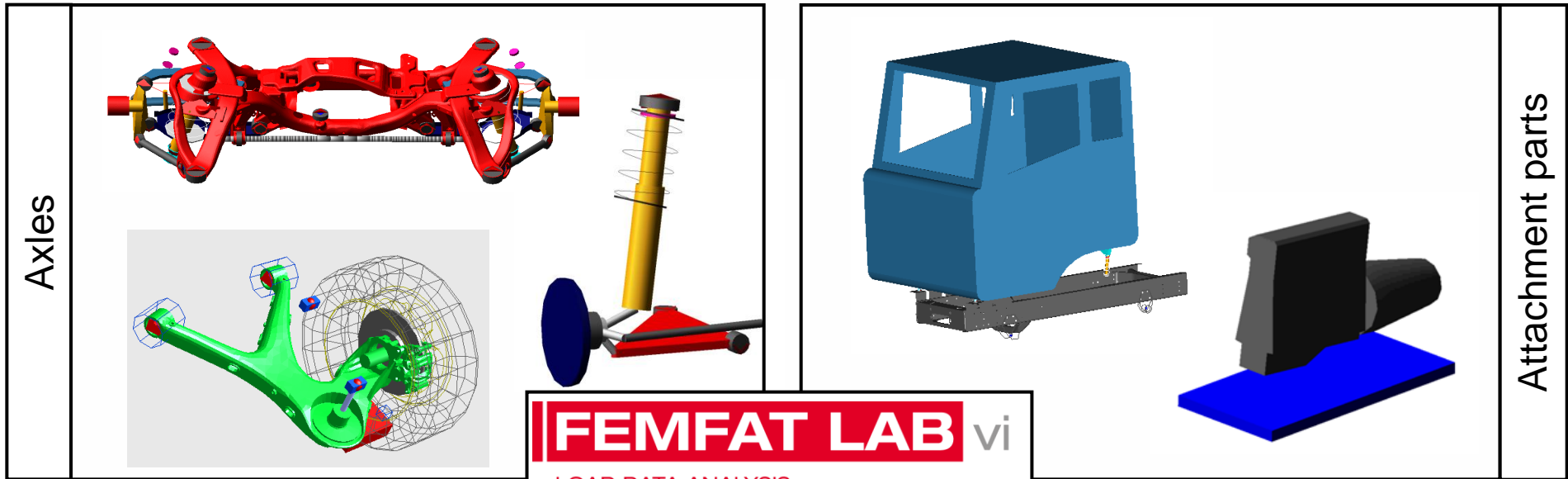


Result check during virtual iteration process basing on:

- signals in time domain (quality check)
- peak-to-peak values of signals in time domain (quantity check)
- signals in frequency domain (PSD)
- relative damage value of simulation compared to measurement



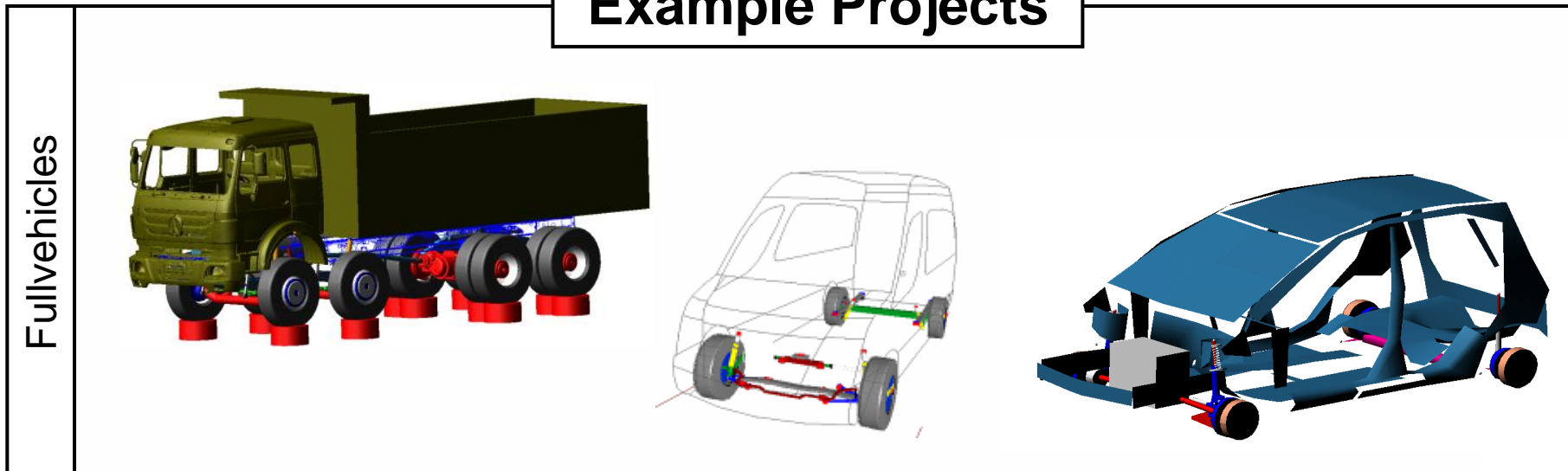
# Virtual Iteration Project Overview



**FEMFAT LAB** vi

LOAD DATA ANALYSIS

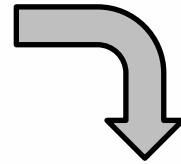
**Example Projects**



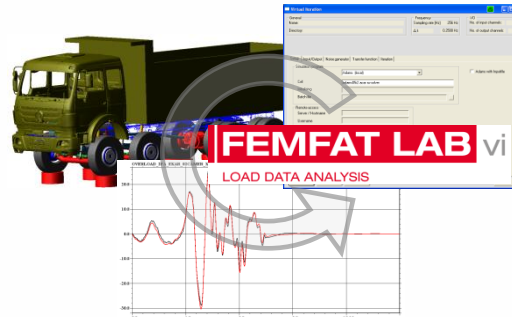


# Virtual Iteration 8x4 Truck

Road load  
data

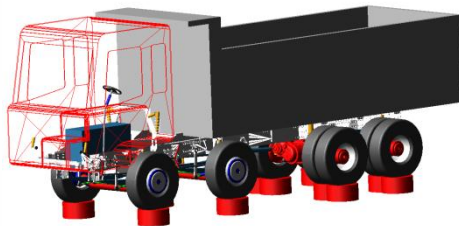


Virtual iteration  
of road surface

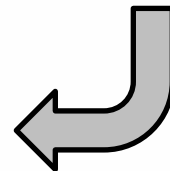


Measurement vehicle

MBS- simulation  
with road surface



New developed vehicle



- Road load data acquisition with benchmark vehicle
- Virtual iteration to invariant road excitation (8-poster)
- Transfer of invariant signals to different vehicle
- Analysis of vertical loaded parts or subsystems possible, e.g. frame (chassis parts not suitable)



# Virtual Iteration 8x4 Truck

## Load (8 channels)

- 8 vertical displacements at the posters



## Desired (measurement)

- Spring displacements
- Vertical accelerations on axles

- MBS model of measurement vehicle
- Virtual iteration of different test tracks (bumps, rough roads, washboards, twisting)

## Model-check (measurement)

- Vertical forces at axle
- Damper forces

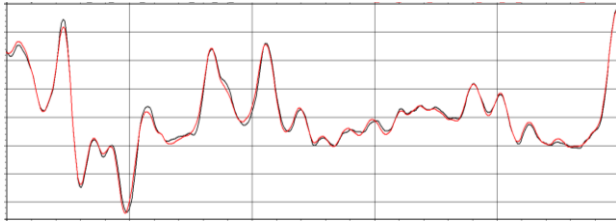


# Virtual Iteration

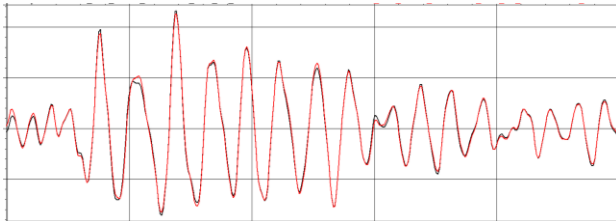
## 8x4 Truck

### Response

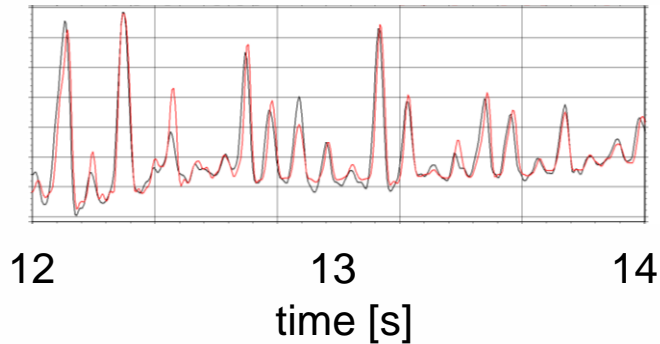
spring  
displ.



vertical  
acc.

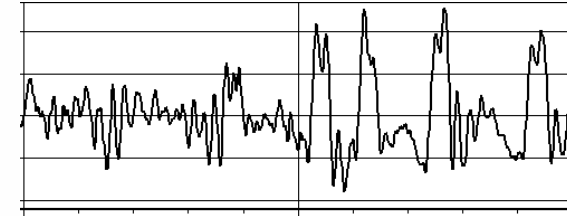


damper  
force  
(check)

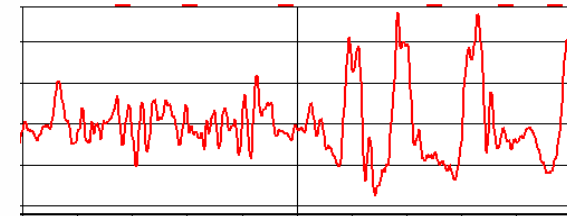


### Drive

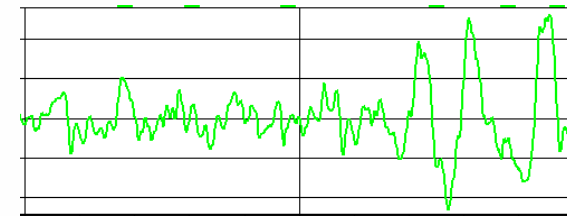
FA1 left



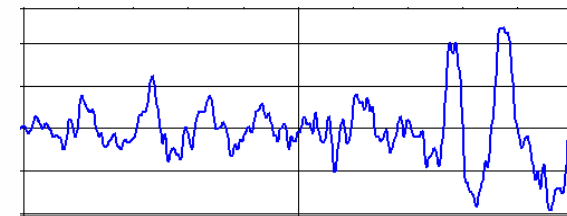
FA2 left



RA1 left



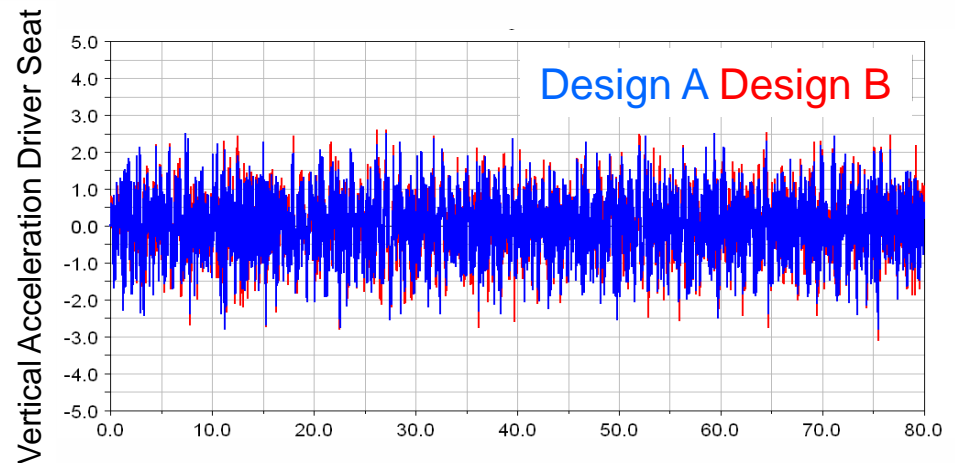
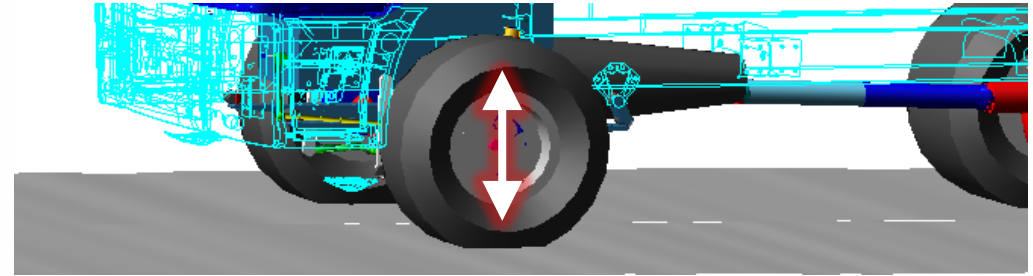
RA2 left



# Virtual Iteration 8x4 Truck

Results of this investigation  
can be used for:

- **Fatigue investigation**  
investigating different concepts  
changing vehicle parameter  
allocate to concept vehicle
- **Comfort investigation**  
modifying suspension parameter  
modifying cab properties



time



**COMFORT VALUES A and B**



# Virtual Iteration Suspension Test Rig



DAIMLER



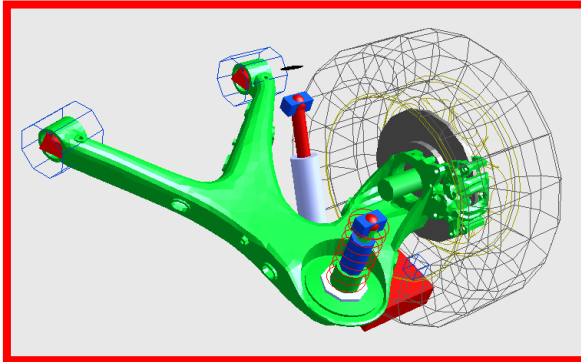
Mercedes-Benz



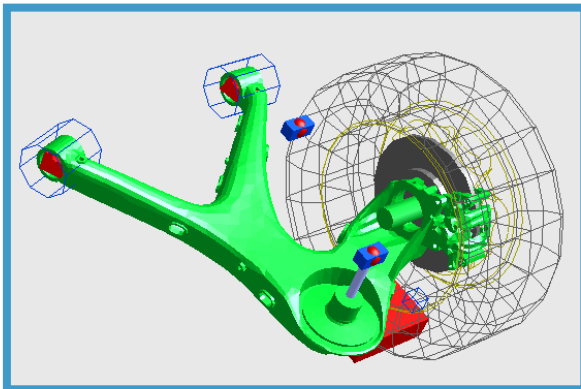
- Endurance strength verification of the chassis is based on proving ground testing (torture track and maneuver like braking, weaving, ...) at Daimler AG
- Development of simplified test rig for semi-trailing arm
- Verification of damage distribution



# Virtual Iteration Suspension Test Rig



vehicle configuration:  
spring and damper

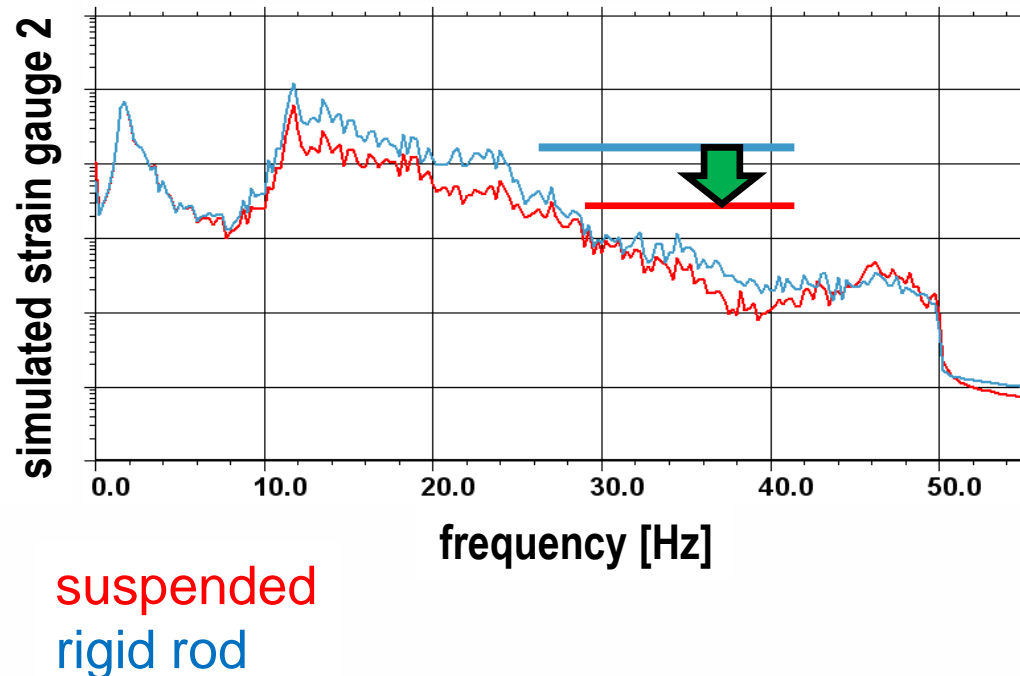


test rig configuration:  
rigid rod, no damper

- Efficiency improvement with a rigid spring/damper
- No cooling of damper necessary
- Replacement of elastomer omitted
- Target: Strain gauge signals unchanged
- Excitation: Torture track, braking, weaving



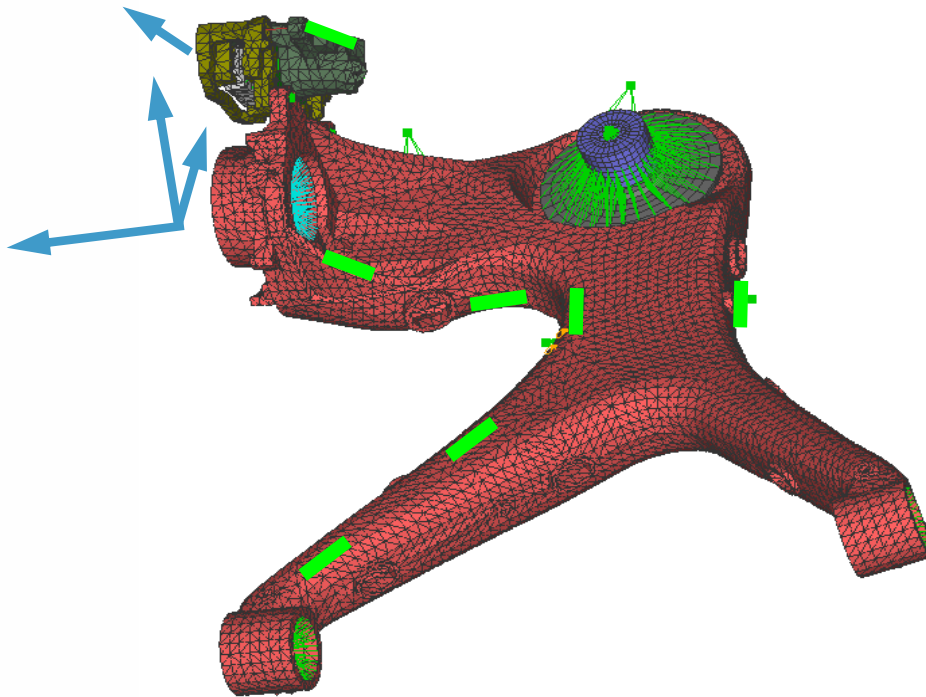
## Why do we need Virtual Iteration?



- Different boundary conditions for test bench: suspended and with rigid rod
- Excitation of both systems with identical loads on wheel hub
- Different strain results inside semi-trailing arm due to changed boundary conditions
- Target: tuning of excitation to gain identical strains at semi-trailing arm



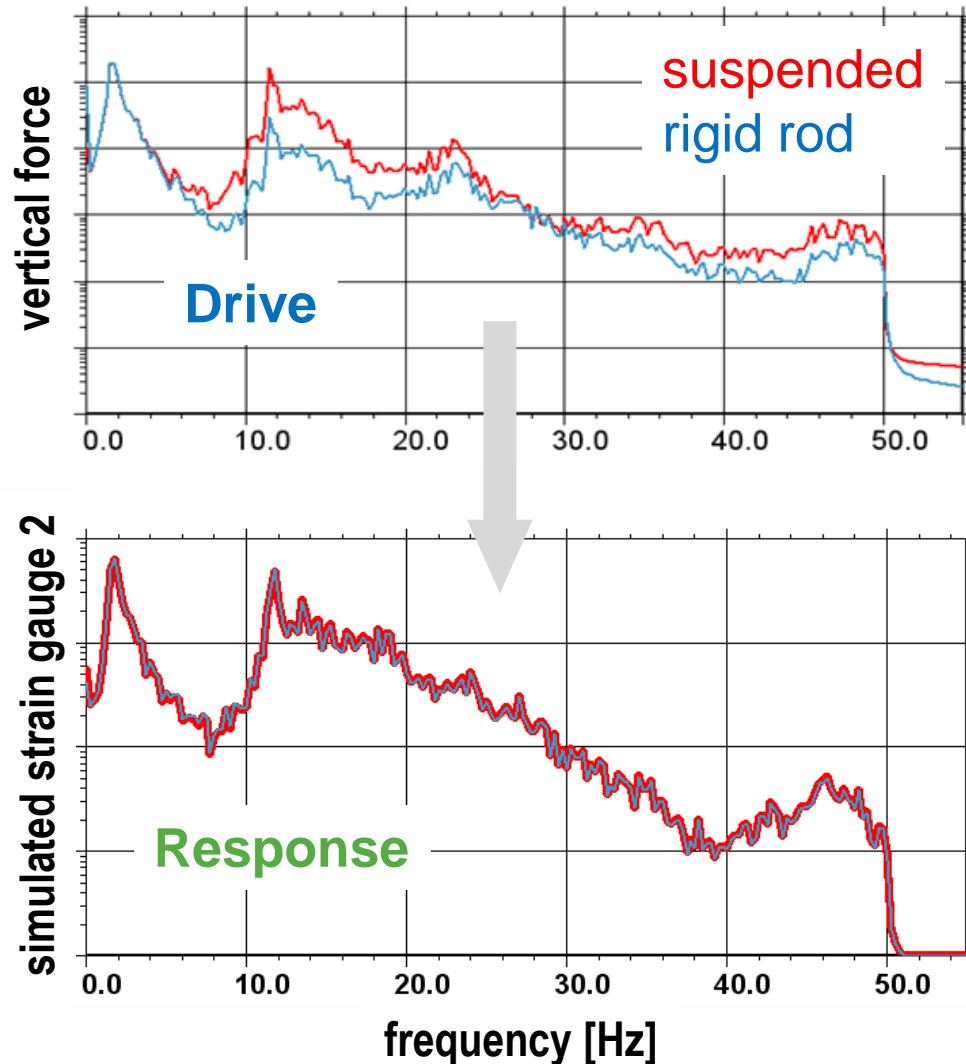
# Virtual Iteration Suspension Test Rig



- **Drive**  
forces and torques applied on wheel hub
- Lateral torque not applied on wheel hub during driving
- Additional constraint during breaking maneuver
- **Response**  
seven strain gauges on semi-trailing link



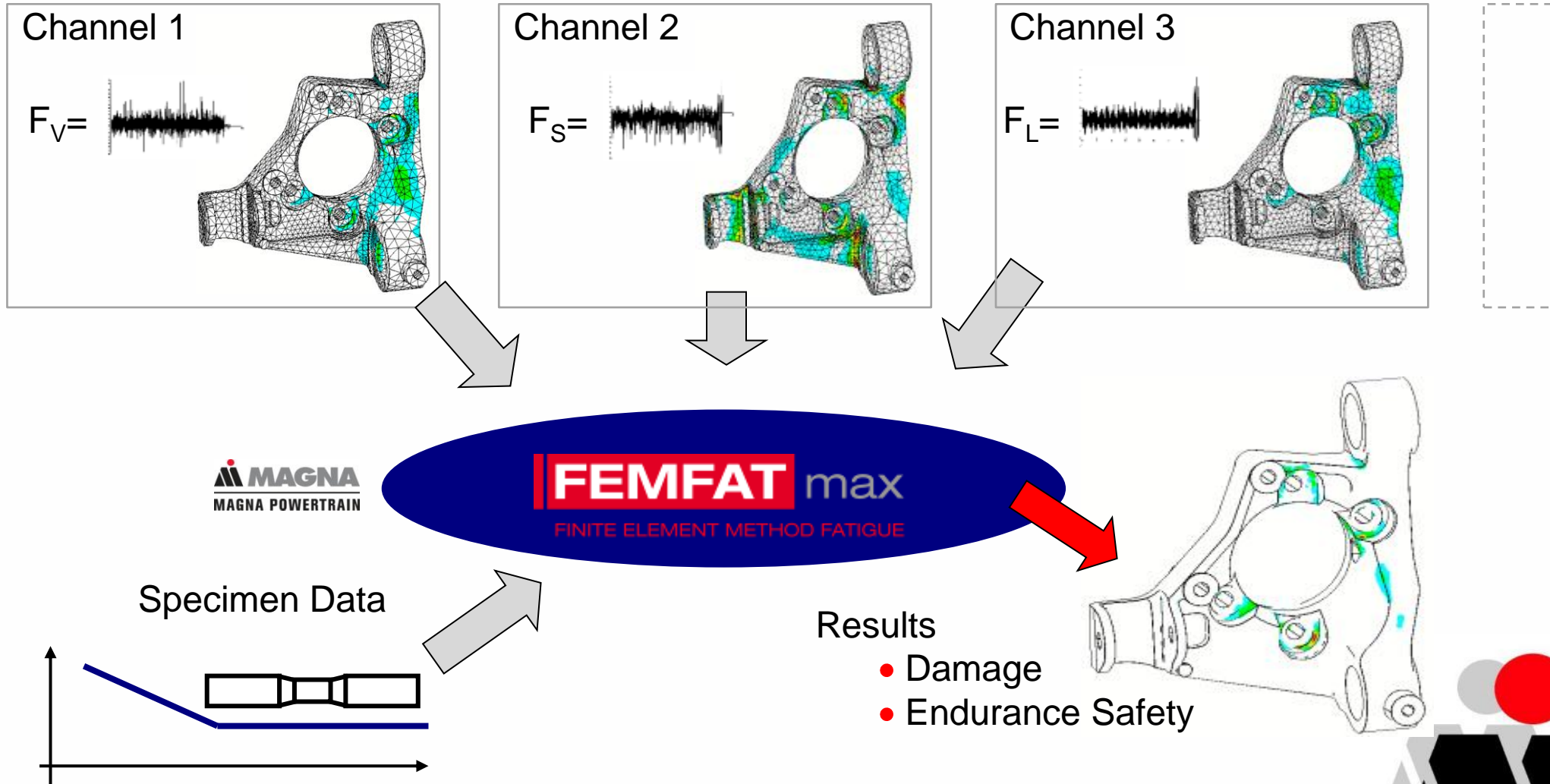
# Virtual Iteration Suspension Test Rig



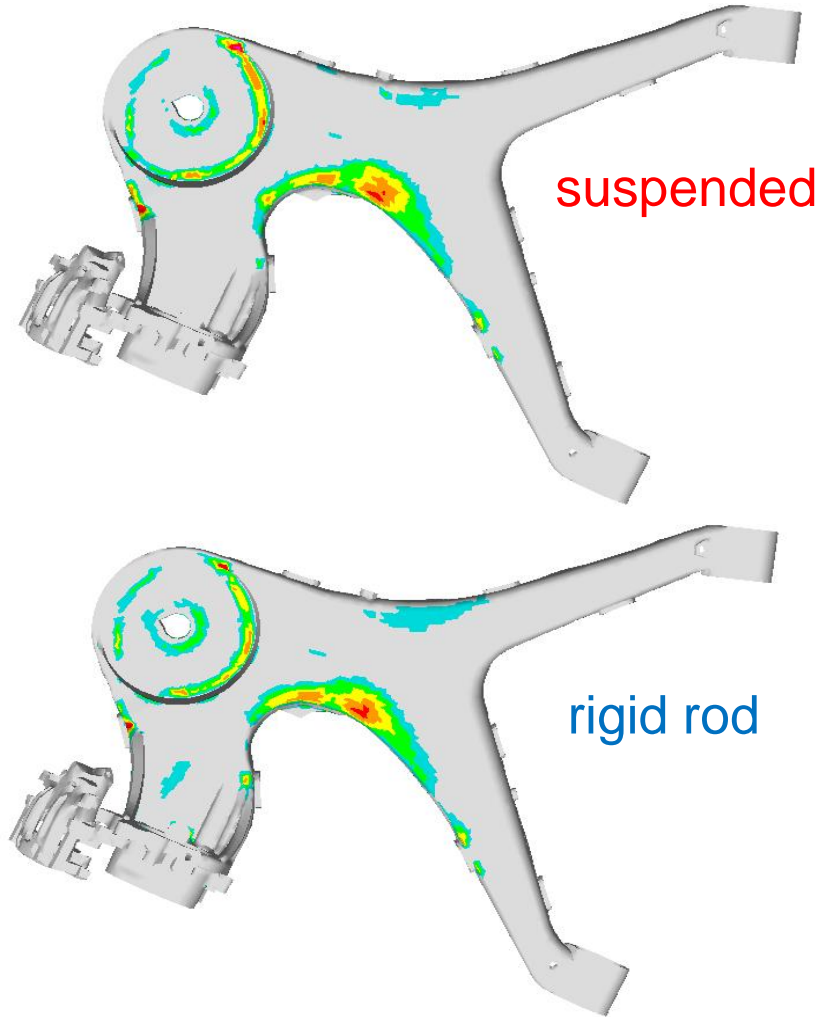
- **Iteration result:**  
Modified time signal for all forces and torques of rigid test bench
- **Simulation of strains by**  
application of modified loads  
on model with rigid rod
- **Goal accomplished:**  
Same strains in both models



# Virtual Iteration Suspension Test Rig



# Virtual Iteration Suspension Test Rig



- Verification of damage location with modified boundary conditions and loads
- Calculation of damage distribution based on simulation results for both models
- Comparison:  
Similar damage distribution with no additional hot spots



## Benefits of Virtual Iteration:

- Simple and cheap measurements for vertical road excitations
- Efficient method to generate absolute displacements (e.g. wheel patch, frame movement)
- No complex tire model required for vertical load
- No road surface scanning required
- Model verification and trimming by additional checking signals
- Absolute fatigue life prediction possible
- Efficient parameter studies and transfer to similar vehicles
- Method applicable for wide range of vehicle components
- Assessment of test bench concepts (viability, simplifications)

